Initialization of Thermofluid models

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Introduction

- Initialization is critical for models with dynamics
 - solution of ODE/DAE depends on initial conditions
 - if consistent initial conditions cannot be found, the model is useless
- Thermofluid models often strongly nonlinear
- Steady-state initialization involves solving large, strongly nonlinear systems of equations
 - sensitivity to initial guess values
 - sensitivity to selection of iteration variables
 - tracing root of problem difficult
 - guess values?
 - errors in the model (e.g. wrong parameters)?
- Troubleshooting is not user friendly
 - understanding of the symbolic/numeric methods
 - understanding the equations of the original model (not encrypted!)
 - equations are rearranged / symbolically solved
 - no avaliable Modelica tool currently gives user friendly GUI support
 - unpredictable time-to-go

Specifying initial conditions - defaults

• Each variable in Modelica has a start attribute

```
model SimpleSystem
  parameter Time tau;
  parameter Real x_start = 2;
  Real x(start = x_start);
  Real u;
equation
  u = if time < 1 then 1 else 2;
  tau * der(x) = - x^2 + u;
end SimpleSystem</pre>
```

- By default, Modelica tools use start values to assign initial values to state variables
- It is possible to log these additional initial equations (Simulation | Setup | Translation | Log selected default initial conditions)

Specifying initial conditions – fixed attribute

 Setting the fixed attribute to true one indicates explicitly that the initial value of the variable is the initial value

```
model SimpleSystem2
parameter Time tau;
parameter Real x_start = 2;
Real x(start = x_start, fixed = true);
Real y;
Real u;
equation
u = if time < 1 then 1 else 2;
tau * der(x) = - x^2 + u;
y = 3*x^2;
end SimpleSystem2</pre>
```

Specifying initial conditions – initial equations

- In Modelica 1.x, initialiation was mainly thought as a tool issue
- Dymola had a run-time interface to specify initial conditions a define free and fixed variables (using data from fixed and start attributes)
- Since Modelica 2.0 (2002): explicit initial equations with arbitrary structure (the old fixed = true mechanism is still available)

```
model SimpleSystem
model SimpleSystem
                                      parameter Time tau;
  parameter Time tau;
  parameter Real x start = 2;
                                      parameter Real x start = 2;
  Real x(start = x start);
                                      Real x(start = x start);
                                      Real v;
  Real y;
  Real u:
                                      Real u;
equation
                                    equation
  u = if time < 1 then 1 else 2; u = if time < 1 then 1 else 2;
  tau * der(x) = -x^2 + u;
                                    tau * der(x) = -x^2 + u;
  y = 3 * x^{2};
                                      v = 3 * x^{2};
initial equation
                                    initial equation
                                      der(x) = 0;
  x = x start;
end SimpleSystem
                                    end SimpleSystem
```

- Initial equations are combined with dynamic equations
- Nonlinear solvers use start attribute for guess values

Specifying initial conditions – Unknown parameters

 Parameters can be freed and determined by further initial equations (beware of initial equation count...)

```
model SimpleSystem
  parameter Time tau;
  parameter Real x start = 2;
  parameter Real y start = 10;
  parameter Real u start(fixed = false, start = 2);
  Real x(start = x start);
  Real y;
  Real u;
equation
  u = if time < 1 then u start else u start + 1;</pre>
  tau * der(x) = -x^2 + u;
  v = 3 * x^{2};
initial equation
  der(x) = 0;
  y = y start;
end SimpleSystem
```

• Fixed attributes can be changed at instantiation (Show Component feature in the Dymola GUI)

Meaningful initial conditions for thermofluid systems

- In some cases, the initial state of a thermofluid system conveniently expressed by giving the values of initial states
- Example: direct steam generation solar plant just before dawn
 - temperature distribution in the collector pipes = ambient temperature
 - given temperatures in the storage volumes, depending on length of shutdown period
 - zero (or negligible) flows (beware of singular conditions)
- In other contexts, starting from an "off-state" is problematic/not required
- Example: power plant model for load change or primary frequency studies
 - range of validity 30-100%
 - piping and instrumentation for startup not included in the model (turbine bypass systems, steam vents, etc.)
- In these cases, the typical transient is the response to a disturbance starting from an equilibrium state (steady-state)
- Fixing approximated initial states can lead to unphysical transients
 - out-of-range mass & heat flow values
 - flow reversal
 - trip conditions

- ...

- Steps of model transformation
 - flattening
 - index reduction
 - elimination of trivial equations / alias variables
 - BLT transformation
 - dynamic problem equations (initial values and parameters)
 - initialization problem (derivatives, algebraic variables)
 - Tearing applied to implicit systems of equations to reduce the number of iteration variables
- Equations solved as explicit assignments \rightarrow no problem
- Implicit linear equations \rightarrow solved without problem if non-singular
- Implicit nonlinear equations \rightarrow iterative methods \rightarrow reasonable guesses required for the iteration variables
- Guess values provided in Modelica by start attributes
 - defined by types
 - defined by modifiers in library models, possibly through parameters
 - defined by direct modifiers on the simulation model

Quick review of Modelica model transformations (cont'd)

- Guess values provided in Modelica by start attributes
- Defined by types

```
type Temperature = Real(unit = 'K', start = 300);
```

• Defined by modifiers in library models, possibly through parameters

```
SI.Pressure p_start;
SI.Pressure p(start = p start);
```

• Defined by direct modifiers on the simulation model

```
model PlantWithStartAttributes
  extends Plant(
    turbine(p_in(start = 1.27e8)),
    drumHP(p(start = 1.32e8)));
end PlantWithStartAttributes;
```

Tearing / Alias variables

- A small fraction of model variables require a guess value to ensure solver convergence
- ~60% alias variables (x = \pm y)
- ~30% assigned in assignment section of torn systems
- Selection of alias and iteration variables in torn systems not unique!
- Alias variable selection in Dymola:
 - highest priority to direct modifiers,
 - intermediate priority to modifiers in libraries
 - lowest priority to type-defined start values
- Tearing variable selection
 - optimal selection: NP-complete problem
 - proprietary heuristics
 - changes w/ small modifications of model
 - changes w/ tool version



Not really object oriented!

- Interactive demo
- dsmodel.mof: how to generate, how to read
- dslog.txt: how to generate, how to read

- Divide and conquer
 - break plant in smaller modules
 - initialize each model w/ suitable boundaries
 - make sure each model is correctly parameterized
- Check dsmodel.mof/dslog.txt and improve start values
- Fix initial states, run transient until equilibrium
 - requires asymptotically stable equilibrium (if not, use simple feedback controllers to stabilize)
 - transient might go wrong because of abnormal mass and energy flows due to unphisical values of initial states
 - example: evaporator with high heat transfer coefficient
 - small error in delta-T fluid-wall → large error in heat flow → condensation/evaporation → bad flow rates (possibly flow reversal)
- Important remark: if the parametrization of the model is incorrect, a steady-state solution might not exist!

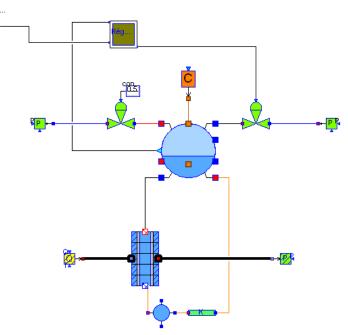
An example of model without steady-state solution

ConsigneNiveauEa

- Natural circulation steam generator
- Nominal operating data:
 - drum pressure 127 bar
 - feedwater pressure 137 bar
 - steam valve outlet pressure 50 bar
 - power from flue gas: 100 MW
 - steam flow: 80 kg/s
- Steam flow rate roughly proportional to steam valve Cv and drum pressure
- Assume now Cv is just 10% smaller than the correct value
 - in order to evacuate 80 kg/s
 drum pressure should be 140 bar
 - feedwater cannot flow from source at lower pressure!

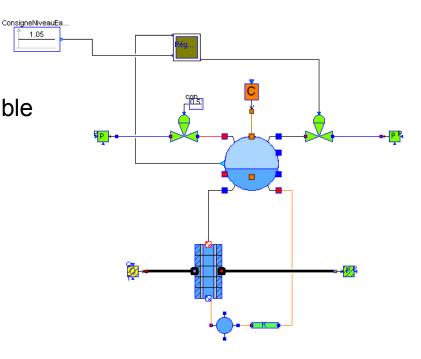


Solution does not exist!



Troubleshooting

- Set initial values of pressures and enthalpies close enough to nominal operating point
- The system has an asymptotically stable ٠ equilibrium thanks to level controller
- Start the simulation
- Drum pressure increases steadily
- Steam flow << feedwater flow
- Too small steam valve →
- Increase steam valve Cv →
- To find the correct Cv:
 - set Cv(fixed = false)
 - set steam_flow(start = 80, fixed = true)



1.05

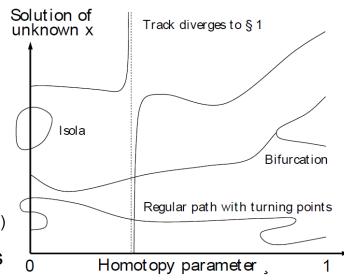
- Setting start values
 - tedious
 - selection of iteration variables can change
 - how to determine good enough values?
 - not object oriented
 - not robust
 - requires high-end skills to troubleshoot models
- A more robust method required
 - guarantee convergence
 - use only well-known design data
 - reasonable defaults for iteration variables
 - no need of directly setting start values
 - object-oriented



Homotopy-based initialization

Homotopy-based initialization: basic ideas

- Simplified problem solved first
 - same variables, slightly modified equations
 - close enough to the actual one
 - steady-state (otherwise structure can change too much!)
 - simpler to solve ("less nonlinar" \rightarrow less sensistive to guess values)
 - guess values possibly provided by default
- Solve convex combination of simplified and actual problem
- Caveat: the problem changes continuously, the solution might not
 - turning points (can be handled by specialized solvers)
 - asymptotes (failure)
 - bifurcations (requires interaction with expert user)
- Specification in Modelica 3.2: homotopy operator
 - homotopy(actual, simplified)
 - during solution of initialization returns λ^* actual + (1λ) *simplified



Simplified models for thermofluid systems

- Linear momentum balance equations with constant coefficients based on nominal operating point
 - pressure loss components $w = w_{nominal} / \Delta p_{nominal} \cdot \Delta p$
 - static head term $\Delta p_{static} = \rho_{nominal} \cdot gH$
 - steam turbine $w = w_{nominal} / p_{nominal} \cdot p_{inlet}$
 - pump: linearized characteristic around nominal operating point

```
// Pump
function df_dq = der(flowCharacteristic, q_flow);
head = homotopy(
    (n/n0)^2*flowChar(q*n0/(n+n_eps)),
    df_dq(q0)*(q-q0) + (2/n0*flowChar(q0) - q0/n0*df_dq(q0))*(n-n0) + head0);
```

```
// Turbine
w = homotopy(Kt*partialArc*sqrt(p_in*rho_in))*sqrtReg(1-(1/PR)^2),
wnom/pnom*p_in);
```

Simplified models for thermofluid systems (cont'd)

- Energy balance equation: nonlinear wh terms
 - use nominal flow rate for energy balance in 1D models for heat exchangers
 - gets rid of most wh terms in a typical model
- Upstream specific enthalpy depending on flow direction
 - assume design direction of flow

```
inStream(inlet.h_outflow));
```

• Flow-dependent heat transfer coefficients

- assume nominal h.t.c. value

- Temperature-specific enthalpy relationship
 - Not too nonlinear in most cases (save phase changes)
 - Do not change (difficult to make it consistent across models)
 - Set rough start values
 - liquid / two-phase / vapour for water
 - within 100-200 K for ideal gases

Simplified models for thermofluid systems (cont'd)

- Controllers acting on flows and controlling energy-related quantities
 - may introduce strong nonlinear coupling between hydraulic and thermal equations
 - simplified model: keep control variable fixed at nominal value (opened feedback loop)
- Controllers with saturations and anti-windup
 - Saturations are strong nonlinearities
 - If known to be in linear regime: remove saturations
 - Else: fix at 0% or 100%
- Control valves
 - Assume flow is nominal flow * opening (regardless of density and pressure drop)
- Initialization not at nominal operating point
 - Simplified model has all setpoints at nominal values
 - Homotopy brings the setpoints to the desired value
 - Different from relaxation transient: quasi-static transformation (less problems if initial guess not accurate – no weird transients)

Performing the homotopy transformation

- Suitable continuation solvers can be used
 - can track turning points
 - efficient interpolation-extrapolation
- Ideally
- no turning points
- no other singularities
- Singularities might arise if wrong parametrization
 - split system into subsystems
 - divide and conquer

Homotopy-based initialization: tool support

- Successful experiments at Politecnico and EDF
 - experimental solver linked to Dymola
 - by M.Sielemann, based on NOX/LOCA solver
 - definitely not user-friendly
- Small-size use cases
 - multibody systems with multiple steady-state configurations
 - analog electronic circuits
 - hydrauliccircuits
 - air conditioning systems
- Large-sized use cases
 - complete combined-cycle power plant models
 - up to 670 iteration variables (!)
 - no need of manual setting of start values
- Preliminary implementation in Dymola 7.5 (not good enough yet)
- Hopefully available soon as standard feature in all Modelica tools

DISCUSSION

References

- M. Sielemann, F. Casella, M. Otter, C. Clauss, J. Eborn, S.E. Mattsson, H. Olsson: Robust Initialization of Differential-Algebraic Equations Using Homotopy. Proceedings of 8th International Modelica Conference, Dresden, Germany, 20-22 March 2011.
- F. Casella, M. Sielemann, L. Savoldelli: Steady-state Initialization of Object-Oriented Thermo-Fluid Models by Homotopy Methods, Proceedings of 8th International Modelica Conference, Dresden, Germany, 20-22 March 2011.