

# The 2014 euRobotics Technology Transfer Award



# 2

## Second prize

Rovereto, Italy, 13 March 2014

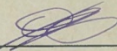


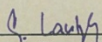
### *Efficient Implementation of Iterative Inverse Kinematics in Real Time Control Architecture*

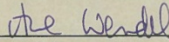
Marina Indri - Politecnico di Torino

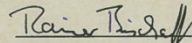
Ivan Lazzeri - Comau Robotics

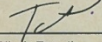
Fabrizio Romanelli - Comau Robotics

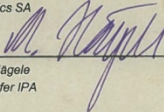
  
Herman Bruyninckx  
KU Leuven

  
Gisbert Lawitzky, Siemens AG

  
Anne Wendel, EUUnited Robotics

  
Rainer Bischoff  
KUKA Laboratories GmbH

  
Nicola Tomatis  
BlueBotics SA

  
Martin Hägele  
Fraunhofer IPA

